

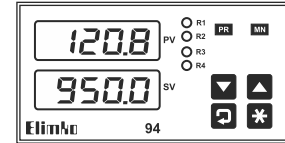
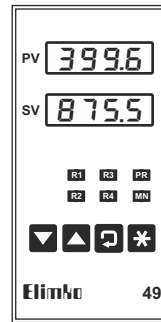
Elimko

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Elimko

E-49 / E-94 Series
Process Controllers
User Manuals



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Elimko _____ E-49 / E-94

- E-49 / E-94 controllers are designed for panel mounting and should be used in an industrial environment.
- The packages of E-49 / E-94 controllers contains; Controller, 2 pieces of mounting clamps, User manual and Guarantee certificate
- After opening the package, please check the contents with the above list. If the delivered product is wrong type, any item is missing or there are visible defects, contact the vendor from which you purchased the product.
- Before installing and operating the controller, please read the user manual thoroughly.
- The installation and configuration of the controller must only be performed by a person qualified in instrumentation.
- Keep the unit away from flammable gases, that could cause explosion.
- Do not use alcohol or other solvents to clean the controller. Use a clean cloth soaked in water tightly squeezed to gently wipe the outer surface of the controller.
- The product life of this instrument is 10 years.



- This controller complies with the European Low Voltage Directive 2006/95/EC, by the application of safety standard TS EN 61010-1. (Pollution degree 2)
- This controller complies with the EMC Directive 2004/108/EC by the application of EMC standard TS EN 61326.

E-49 / E-94 _____ **Elimko**

1. DEFINITION

E-49 / E-94 Series Controllers are designed to use On/Off and PID Control Techniques, by using new generation microcontrollers.

The dimensions of the E-49 controllers are 48x96 mm & E-94 controllers are 96x48 mm confirming IEC/TR 60668 standard. The controllers have two 4-digit seven segment led displays each capable of displaying numeric values from -1999 to 9999 and 4-character alphanumeric values messages. The universal inputs (T/C, R/T, mV, mA) are configurable and measured with 16-bit resolution. These electronic units, have high reading accuracy with high measurement sensitivity, don't contain any loose mechanical parts, and provide limitless reliability. They are calibrated in order not to be defected by time and exterior factors. High input impedance, protection of the system from loss of signal, E-49 / E-94 have two separate, 4-digit, display to display process value and set values within the range of -1999 to 9999.

For all industrial applications for the measurement and control of; temperature pressure, level speed current-voltage, resistance and other physical features, also for areas such as; Iron-Steel, Cement, Chemistry, Food, Plastic, Petrochemistry, Refineries, Ceramics, Glass and industries this unit is ideal.

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Elimko _____ E-49 / E-94

2. TECHNICAL SPECIFICATIONS

Input Types	Thermocouple (TC): B, E, J, K, L, N, R, S, T, U Resistance Thermometer (RT) : Pt-100 Current : 0-20 mA, 4-20 mA (Linear) Voltage : 0-50 mV, 0-1 V, 0.2-1 V (Linear)
Control Output	Relay : SPST-NO 250V AC, 5A Current : 0-20 mA, 4-20 mA (Isolated) Pulse : 24V DC, 25 mA (for SSR)
Alarm Outputs	Relay : SPST-NO 250V AC, 5A
Display Type	E-49: 2 x 4 digit 7 mm 7 segment led display E-94: 2 x 4 digit 14 mm 7 segment led display
Accuracy	Thermocouple : (±0.5% of the reading value or ±1 °C) ±1 digit max. Pt-100 : (±0.5% of the reading value or ±1 °C) ±1 digit max. Analog Input : ±0.5% FS ±1 digit max.
Analog Digital Converter	16 bit
Digital Analog Converter	12 bit
Control Type	On / Off, PID
Operating Voltage	85-265 V AC / 85-375 V DC 20-60 V AC / 20-85 V DC

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E-49 / E-94 _____ **Elimko**

2. TECHNICAL SPECIFICATIONS

Power Consumption	10 VA
Protection Class	Front Panel : IP 66 (NEMA 4X) Rear Case : IP 20
Operating Temperature	-10 °C, +55 °C (+14 °F, +131 °F) (with no condensation or icing)
Storage Temperature	-25 °C, +65 °C (-13 °F, +149 °F) (with no condensation or icing)
Relay Mechanical Life	10.000.000 operation*
Relay Electrical Life	>1.000.000 operation (under 1/10 of load)
Memory	EEPROM (100.000 max. Write-erase)
Weight	220 gr

* The relay life differs according to the usage configuration. When the relays are old, their contacts could melt or burn out.

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3. TYPE CODING

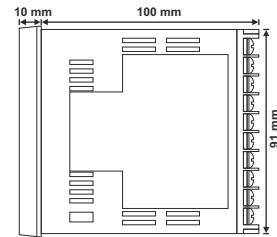
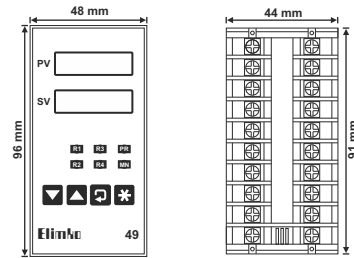
0: No Output
1: 1 Analog Output

E-49 / E-94 -W - X - 0 - Z

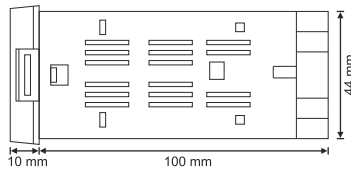
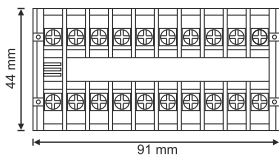
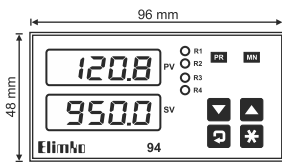
0: No Relay
1: 1 Relay
2: 2 Relays
3: 3 Relays
4: 4 Relays
5: 5 Relay, 1 Pulse
6: 2 Relays, 2 Pulse
7: 3 Relays, 1 Pulse

0: 85-265 V AC/85-375 V DC
1: 20-60 V AC/20-85 V DC

4. DIMENSIONS (E-49)



4. DIMENSIONS (E-94)

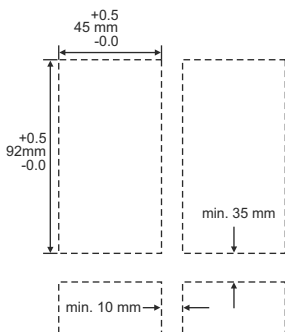


5. PANEL MOUNTING

- E-49 / E-94 controllers should be installed inside a suitable grounded metal enclosure (panel). This must prevent the live parts being accessible to human hands and metal tools.
- E-49 / E-94 controllers does not include a power switch. Therefore, the power supply to the controller and power outputs must be wired through the proper fuse or circuit breaker.
- To minimize the pick-up of electrical noise, the wiring of low voltage lines, particularly the sensor input should be routed away from the high-current power cables. Where it is not possible, use shielded cables with the shield grounded at both ends.
- The cables used for powering the controller and the power outputs must conform to the standards IEC 60245 and IEC 60227.

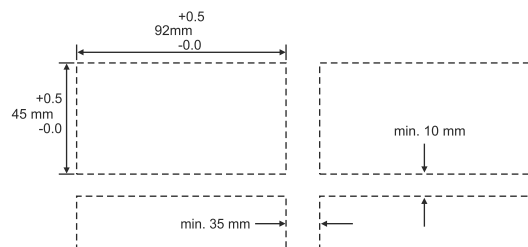


5. PANEL MOUNTING (E-49)



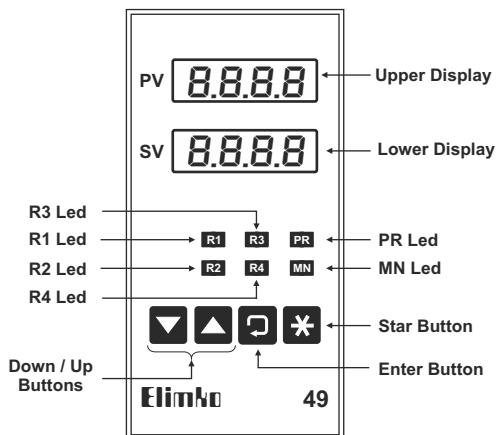
- Cut a hole in the panel. (See the figure for overall dimensions.)
- Slide the controller into the cutout from the front of the panel.
- Fit the mounting clamps to the up and down sides of controller, ensuring the lugs are located in their slots.
- Fasten the mounting clamps using the retaining screws.

5. PANEL MOUNTING (E-94)

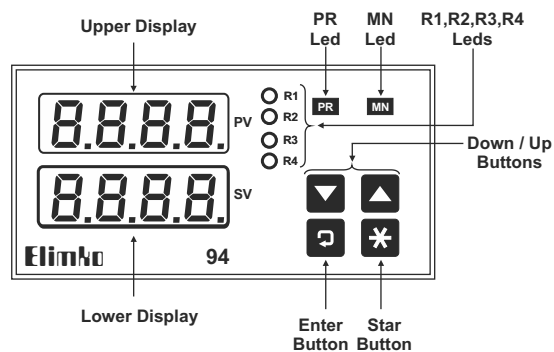


- Cut a hole in the panel. (See the figure for overall dimensions.)
- Slide the controller into the cutout from the front of the panel.
- Fit the mounting clamps to the up and down sides of controller, ensuring the lugs are located in their slots.
- Fasten the mounting clamps using the retaining screws.

6. FRONT PANEL (E-49)



6. FRONT PANEL (E-94)



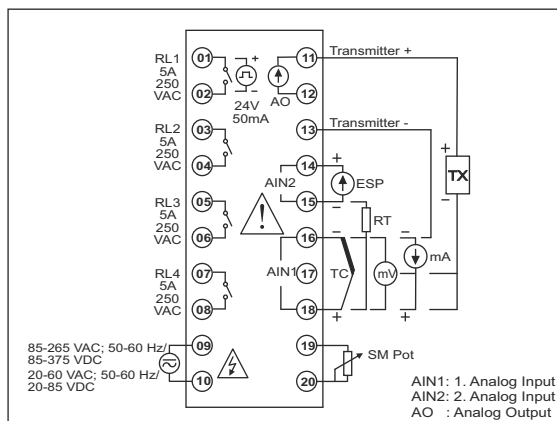
6. FRONT PANEL

- R1 Led** When lit, it indicates that RL1 output is active.
- R2 Led** When lit, it indicates that RL2 output is active.
- R3 Led** When lit, it indicates that RL3 output is active.
- R4 Led** When lit, it indicates that RL4 output is active.
- PR Led** When lit, it indicates that the controller is in the configuration mode.
- MN Led**
 - When lit, it indicates that the controller is in manual mode.
 - MN led will also flash when the auto-tuning is in progress.
- Upper Display**
 - While in normal operation, it displays the process value or error message.
 - While in configuration pages, it displays the name of the parameters.
- Lower Display**
 - While in normal operation, it displays the control set point (Automatic mode) or manual output (Manual mode).
 - While in configuration pages, it displays the parameter value.

6. FRONT PANEL

- Star Button**
 - When pressed together with button, password is asked for entering the configuration page.
 - While in configuration pages, pressing this button reverts to normal operation.
 - While in normal operation, pressing this button for duration 3 seconds, toggles between automatic and manual mode.
 - This operation is disabled if the \overline{mnPr} parameter in page αCnF is set to $d5b$ or if the $EtYP$ parameter in αCnF page is set $nanE$.
 - While in normal operation, pressing this button acknowledges the latched alarms if configured ($RXLt = Enb$).
- Enter Button**
 - When pressed together with button, password is asked for entering the configuration page.
 - While in configuration pages, pressing this button selects the next parameter.
 - While in configuration pages, pressing this button for duration 2 seconds, returns to the top of the page.
 - While in normal operation, pressing this button selects the next parameter in operator page.
- Down Up Buttons**
 - While in normal operation, these buttons can be used to edit the control set point (Automatic mode) or manual output (Manual mode).
 - While in configuration, these buttons can be used to select the configuration pages and to edit the parameters.

7. CONNECTION DIAGRAM



The labels on the sides of the controller identify the ordering code (Type), serial number and wiring connections. The controller options are also indicated on the wiring diagram.

7. CONNECTION DIAGRAM

- The terminals 01 to 10 are electrically live. While the instrument is powered, never touch to these terminals.
- Before operating the controller, ensure that the controller is correctly configured. Incorrect configuration could result in damage to the process being controlled.



8. OPERATING PAGES

- When the controller power is switched on, it runs through a self-test sequence for about 2 seconds and displays the version number and then enters into normal operation.
- The controller has two basic modes of operation:
 - Automatic mode in which the output is automatically adjusted to maintain the process value at the control set point.
 - Manual mode in which one can adjust the output independently of the control set point.
- MN led indicates the operation mode of the controller. It lights while controller is in manual mode.

8. OPERATING PAGES

- While in normal operation, pressing \otimes button for duration 3 seconds, toggles between automatic and manual mode. This operation is disabled if the \overline{mPr} parameter in page αCnF is set to $d5b$ or if the ζtYP parameter in αCnF page is set $nonE$.
- In normal operation the process value is displayed in the upper display, the control set point (Automatic mode) or manual output (Manual mode) is displayed in the lower display.
- The normal operation state and the frequently used parameters are in the operator page. These parameters can be accessed by \square button.
- The parameters in the operator page differ according to the operation mode.

9. AUTOMATIC MODE

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
234 00	Process Value	EU			
	Control Set Point	EU		∇ / Δ	$SP_{LL} - SP_{HL}$ ⁽¹⁾
αU 00	Manual Output ⁽²⁾	%	$\zeta tYP \neq nonE$	∇ / Δ	
P5P 00	Progressive Set Point	EU	$SP_{Pr} \neq oFF$	∇ / Δ	
R15P 00	Alarm-1 Set Point	EU	$R1tP \neq oFF$	∇ / Δ	+999 - 9999
R25P 00	Alarm-2 Set Point	EU	$R2tP \neq oFF$	∇ / Δ	+999 - 9999
R35P 00	Alarm-3 Set Point	EU	$R3tP \neq oFF$	∇ / Δ	+999 - 9999
R45P 00	Alarm-4 Set Point	EU	$R4tP \neq oFF$	∇ / Δ	+999 - 9999

⁽¹⁾ If the set point source is external ($SP5r \neq Int$), this adjustment is not valid.

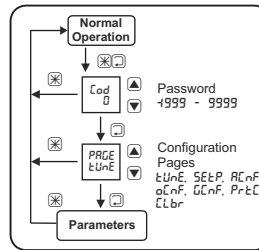
⁽²⁾ With the control type as open loop valve control ($\zeta tYP = bnd$), this screen is used for valve direction, instead of manual output value. ($5tP =$ Valve inactive, $\zeta L5 =$ Closing Valve, $\alpha Pn =$ Opening Valve)

10. MANUEL MODE

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
234 500	Process Value	EU	$\zeta tYP = 5Co$ Single Sided (+) PID Control		
	Manual Output	%		∇ / Δ	$5oLL - 5oHL$
234 500	Process Value	EU	$\zeta tYP = dCo$ Double Sided(+/-) PID Control		
	Manual Output	%		∇ / Δ	$doLL - doHL$
234 500	Process Value	EU	$\zeta tYP = Pfb$ Feedback Valve Control		
	Manual Output	%		∇ / Δ	$5oLL - 5oHL$
234 5tP	Process Value	EU	$\zeta tYP = bnd$ Open-Loop Valve Control		
	Valve Direction ⁽¹⁾			∇ / Δ	Vana Kıs / Aç
R15P 00	Alarm-1 Set Point	EU	$R1tP \neq oFF$	∇ / Δ	+999 - 9999
R25P 00	Alarm-2 Set Point	EU	$R2tP \neq oFF$	∇ / Δ	+999 - 9999
R35P 00	Alarm-3 Set Point	EU	$R3tP \neq oFF$	∇ / Δ	+999 - 9999
R45P 00	Alarm-4 Set Point	EU	$R4tP \neq oFF$	∇ / Δ	+999 - 9999

⁽¹⁾ $5tP =$ Valve inactive, $\zeta L5 =$ Closing Valve, $\alpha Pn =$ Opening Valve

11. CONFIGURATION PAGES



Input to Configuration Pages

- The fundamental characteristics of the controller are specified in configuration pages. These pages:
 - $tUnE =$ PID Tuning Page
 - $5EtP =$ Set Points Configuration Page
 - $RCnF =$ Alarm Configuration Page
 - $\alpha CnF =$ Control and Output Configuration Page
 - $GCnF =$ General Configuration Page
 - $PrtC =$ Security Adjustments Page
 - $\zeta Lbr =$ Calibration Page

- In order to access the configuration pages, \otimes and \square buttons are pressed simultaneously.
- After this operation PR led lights and ζod message and \square are displayed in the upper and lower displays respectively.
- ∇ and Δ buttons are used to adjust the security code in the lower display. When \square button is pressed $tUnE$ page is accessed.
- The factory setting of the security code is "10".
- The security code is defined by the parameter $5Cod$ in $PrtC$ page.

11. CONFIGURATION PAGES

- If the entered security code is correct all the configuration pages can be accessed and all the parameters in the configuration pages can be edited. Otherwise $dPrL$ and $RPrL$ parameters in $PrtC$ page define the access and edit levels of parameters.
- ∇ and Δ buttons are used to select the configuration pages while $PRGE$ message is displayed in the upper display. \square button select the parameters in a page sequentially. \square button returns to the top of the page if it pressed for duration of 2 seconds, while in configuration pages. \otimes button reverts to normal operation, while in configuration pages.

PID Tuning Page ($PRGE-tUnE$)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
Rt oFF	Auto-Tune ⁽¹⁾	Table 4	$\zeta tYP \neq nonE$ $\zeta tYP \neq bnd$	∇ / Δ	Table 4
Pb-1 200	Proportional Band-1 (For "+" Directed Control Outputs)	EU	$\zeta tYP \neq nonE$	∇ / Δ	0.1 - 9999
Pb-2 200	Proportional Band-2 (For "-" Directed Control Output)	EU	$\zeta tYP = dCo$	∇ / Δ	0.1 - 9999
It 28	Integral Time (If "oFF", integral is inactive)	s	$\zeta tYP \neq nonE$	∇ / Δ	oFF, 1-9999
dT 7	Derivative Time (If "oFF", derivative is inactive)	s	$\zeta tYP \neq nonE$	∇ / Δ	oFF, 1-2500
HYS 0.1	Hysteresis	EU		∇ / Δ	0.0 - 9999

⁽¹⁾ Auto-tune operation is inhibited in manual mode.

Set Point Configuration Page (PRGE=SEtP)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
SP5r Int	Set Point Source	Table 10		▼ / ▲	Table 10
SPLL +999	Set Point Lower Limit	EU		▼ / ▲	+999 - SPHL
SPHL 9999	Set Point Upper Limit	EU		▼ / ▲	SPLL - 9999
SPrr 00	Set Point Ramping Rate (For fastest change, enter "oFF")	EU/min		▼ / ▲	oFF, 0.1-600

Alarm Configuration Page (PRGE=ALnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
AL1P oFF	Alarm-1 Type	Table 8		▼ / ▲	Table 8
AL1H 05	Alarm-1 Hysteresis	EU	AL1P ≠ oFF	▼ / ▲	00 - 9999
AL1L d5b	Alarm-1 Lock (1)	Table 3	AL1P ≠ oFF	▼ / ▲	Table 3

Alarm Configuration Page (PRGE=ALnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
AL2P oFF	Alarm-2 Type	Table 8		▼ / ▲	Table 8
AL2H 05	Alarm-2 Hysteresis	EU	AL2P ≠ oFF	▼ / ▲	00 - 9999
AL2L d5b	Alarm-2 Lock (1)	Table 3	AL2P ≠ oFF	▼ / ▲	Table 3
AL3P oFF	Alarm-3 Type	Table 8		▼ / ▲	Table 8
AL3H 05	Alarm-3 Hysteresis	EU	AL3P ≠ oFF	▼ / ▲	00 - 9999
AL3L d5b	Alarm-3 Lock (1)	Table 3	AL3P ≠ oFF	▼ / ▲	Table 3
AL4P oFF	Alarm-4 Type	Table 8		▼ / ▲	Table 8
AL4H 05	Alarm-4 Hysteresis	EU	AL4P ≠ oFF	▼ / ▲	00 - 9999
AL4L d5b	Alarm-4 Lock (1)	Table 3	AL4P ≠ oFF	▼ / ▲	Table 3

(1) Pressing (X) button acknowledges the latched alarms if ALxL is Enb while in normal operation.

Control and Output Configuration Page (PRGE=OLnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
CTYP 5Co	Control Type	Table 9		▼ / ▲	Table 9
CFrn rEu	Control Form	Table 5	CTYP ≠ nonE	▼ / ▲	Table 5
CPrd 2	Control Period	s	CTYP ≠ nonE	▼ / ▲	1 - 250
MANP d5b	Manual Mode Select	Table 3	CTYP ≠ nonE	▼ / ▲	Table 3
trtn 100	Motor Valve Travel Time	s	CTYP = bnd	▼ / ▲	10 - 2500
dbnd 05	Control Output Death Band	%	CTYP ≠ nonE	▼ / ▲	0.1 - 250
SoLL 00	Single Sided(+) Control Output Lower Limit	%	CTYP ≠ nonE CTYP ≠ dCo	▼ / ▲	00 - 5oAr
SoHL 1000	Single Sided (+) Control Output Upper Limit	%	CTYP ≠ nonE CTYP ≠ dCo	▼ / ▲	5oAr - 1000
5oAr 500	Single Sided (+) Control Output Manual-Reset Value	%	CTYP ≠ nonE CTYP ≠ dCo	▼ / ▲	5oLL - 5oHL
doLL +000	Double Sided (+/-) Control Output Lower Limit	%	CTYP = dCo	▼ / ▲	+000 - doAr

Control and Output Configuration Page (PRGE=OLnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
doHL 1000	Double Sided (+/-) Control Output Upper Limit	%	CTYP = dCo	▼ / ▲	doAr - 1000
doAr 00	Double Sided (+/-) Control Output Manual-Reset Value	%	CTYP = dCo	▼ / ▲	doLL - doHL
PonC 0	PID Control Power-On Behaviour	Table 13	CTYP ≠ nonE	▼ / ▲	Table 13
RL1d Co-1	1.Relay (RL1) Function	Table 7		▼ / ▲	Table 7
RL2d Co-2	2.Relay (RL2) Function	Table 7		▼ / ▲	Table 7
RL3d RL-3	3.Relay (RL3) Function	Table 7		▼ / ▲	Table 7
RL4d RL-4	4.Relay (RL4) Function	Table 7		▼ / ▲	Table 7
AO1d Co-1	1.Analog Output (AO1) Function	Table 11		▼ / ▲	Table 11
AO1r 4-20	1.Analog Output (AO1) Scalar	Table 12		▼ / ▲	Table 12

Control and Output Configuration Page (PRGE=OLnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
5rUL 1889	Motor-Valve Fully-Closed Position		CTYP = PfB	▼ / ▲	Valve Close / Valve Open Save Position
5rUH 3756	Motor-Valve Fully-Open Position		CTYP = PfB	▼ / ▲	Valve Close / Valve Open Save Position

General Configuration Page (PRGE=GLnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
INP1 1	1.Analog Input (AIN1) Type (For Process Value Measurement)	Table 14		▼ / ▲	Table 14
INP2 4R20	2.Analog Input (AIN2) Type (External Set Point input)	Table 2		▼ / ▲	Table 2
dP 1	Decimal Point (1)			▼ / ▲	0 - 3
2ErO 00	Analog Input Scale Lower Value (Linear Input types)	EU		▼ / ▲	+999 - 9999

General Configuration Page (PRGE=GLnF)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
SPAn 4000	Analog Input Scale Upper Value (Linear Input types)	EU		▼ / ▲	+999 - 9999
trLL 00	Retransmission Low Limit	EU		▼ / ▲	+999 - trHL
trHL 4000	Retransmission High Limit	EU		▼ / ▲	trLL - 9999
UnIt oC	Temperature Unit (2)	Table 6	INP != TC / RT	▼ / ▲	Table 6
oFSt 00	Temperature Offset Value	EU	INP != TC / RT	▼ / ▲	+000 - 1000
FLtr 05	Measurement Filter Coefficient	EU		▼ / ▲	0.1 - 100
Snbr H1	Sensor Broken Behaviour	Table 1		▼ / ▲	Table 1

(1) Decimal Point is specified by the dP parameter. But if 1.Analog Input Type (INP1) is TC or RT and the dP parameter is greater than "1", Decimal Point = 1 assumed. When the dP parameter is edited, all the parameters with EU unit should be readjusted.

(2) The EU (Engineering Unit) used in tables, thermocouples and resistance thermometer input type units °C or °F, and for linear inputs types, are the controlled measurement unit.

Security Adjustments Page (PRGE=PrL)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
5C _{od} ID	Password Set Value ⁽¹⁾			▼ / ▲	1999 - 9999
Rr _{tn} oFF	Auto Return Time ⁽²⁾ (cancelled if oFF)	s		▼ / ▲	oFF, 5 - 25
dPr _L 5	Parameter Access Level	Table 15		▼ / ▲	Table 15
AP _r _L 2	Parameter Edit Level	Table 16		▼ / ▲	Table 16
CP _r _L d5b	Calibration Page Access	Table 3		▼ / ▲	Table 3
FC5k oFF	Return to Factory Settings ⁽³⁾	Table 4		▼ / ▲ ☒	Table 4 Approval

- ⁽¹⁾ Factory setting of password is "10".
- ⁽²⁾ The value of Rr_{tn} parameter defines the auto return time to normal operation, if there is no button operation. If it is set the oFF, auto return is disabled.
- ⁽³⁾ The factory settings of the parameters are given in "Display" column (except the CP_r_L page). The parameter values in the CP_r_L page are the typical.

Calibration Page (PRGE=CLbr)

Display	Explanation	Unit	Access Conditions	Button	Key Function / Setting Interval
50 _{nv} 583z	1. Analog Input (AIN1) 50 mV Calibration ⁽¹⁾			☒	Save Calibration Value
00 ^o C 83z	1. Analog Input (AIN1) 0.0°C Calibration (with Type K TC) ⁽²⁾			☒	Save Calibration Value
390 _r 5545	1. Analog Input (AIN1) 390Ω Calibration ⁽³⁾			☒	Save Calibration Value
20 _{ra} 8845	1. Analog Input (AIN1) 20 mA Calibration ⁽⁴⁾			☒	Save Calibration Value
in _{2H} 8845	2. Analog Input (AIN2) 20 mA Calibration ⁽⁴⁾			☒	Save Calibration Value
Ro _{IL} 1600	1. Analog Output (AO1) 4 mA Calibration ⁽⁵⁾			▼ / ▲	1300 - 3000
Ro _{IH} 1400	1. Analog Output (AO1) 20 mA Calibration ⁽⁶⁾			▼ / ▲	6500 - 8191

○ The basic calibration of the controller is highly stable and set in the factory. Any erroneous operation in the CLbr page will corrupt the calibration parameter, and measurements will be faulty. The calibration parameters of the controller can be reinstalled in the CP_r_L page. If accurate calibration devices are not available, entering to the CLbr page is not advised.



Calibration Page (PRGE=CLbr)

- ⁽¹⁾ Set the calibrator as a millivolt source and adjust the calibrator output 50.000 mV. Apply the calibrator output to the input terminals 16(-) and 18(+) of the controller. Select this parameter and press ☒ and ▼ buttons simultaneously to store the parameter.
- ⁽²⁾ Set the calibrator to Type K thermocouple and adjust the calibrator output 0.00 °C. Apply the calibrator output to the input terminals 16(-) and 18(+) of the controller. Select this parameter and press ☒ and ▼ buttons simultaneously to store the parameter.
- ⁽³⁾ Set the calibrator as a resistance source and adjust the calibrator output 390.00 Ω. Short circuit the terminals 16 and 18 of the controller. Apply the calibrator output to the input terminals 15 and 16 of the controller. Select this parameter and press ☒ and ▼ buttons simultaneously to store the parameter.
- ⁽⁴⁾ Set the calibrator as a milliamper source and adjust the calibrator output 20.00 mA. For 1.Analog Input, short circuit the terminals 17 and 18 of the controller and apply the calibrator output to the input terminals 16(-) and 17(+). For 2.Analog Input, apply the calibrator output to the input terminals 14(+) and 15(-) of the controller. Select this parameter and press ☒ and ▼ buttons simultaneously to store the parameter.
- ⁽⁵⁾ Set the calibrator as a milliamper meter. Connect the output terminals 11(+) and 12(-) of the controller to the calibrator input. Select this parameter and using ▼ and ▲ buttons adjust the parameter until the calibrator reading is equal to 4.00 mA. Press ☒ or ☒ button to store the parameter.
- ⁽⁶⁾ Set the calibrator as a milliamper meter. Connect the output terminals 11(+) and 12(-) of the controller to the calibrator input. Select this parameter and using ▼ and ▲ buttons adjust the parameter until the calibrator reading is equal to 20.00 mA. Press ☒ or ☒ button to store the parameter.

12. TABLES

Table 1	Table 2	Table 3	Table 4	Table 5	Table 6	Table 7	Table 8
Lo Lower The Process Value	0R20 0-20mA (Linear)	d5b Disable	oFF Off	dIr Direct	oC °C	Co-1 "+ Directed Control Output	oFF Off
Hi Higher The Process Value	4R20 4-20mA (Linear)	End Enable	on On	rEu Revers	oF °F	Co-2 "- Directed Control Output	Lo Low Alarm (Absolute)
						do-1 On / Off Heater Output	Hi High Alarm (Absolute)
						do-2 On / Off Cooler Output	LoD Low Deviation (Relative)
						RL-1 Alarm-1	HiD High Deviation (Relative)
						RL-2 Alarm-2	LoB Band Alarm (In)
						RL-3 Alarm-3	HiB Band Alarm (Out)
						RL-4 Alarm-4	
						RL-R Reserve	
						RL-b Reserve	
						RL-c Reserve	
						RL-d Reserve	
						RL-o Reserve	
						RL-H Reserve	
						RL-E Reserve	

12. TABLÖLAR

Table 9	Table 10	Table 11	Table 12	Table 13	Table 14
noN No Control	inE Over The Unit	Co-1 "+ Directed Control Output	0-20 0-20mA	0 Run with the latest Control Values	b Type B (TC)
5Co Single-Sided (+) PID Control	ErE Over The 2.Analog Input (AIN2)	Co-2 "- Directed Control Output	20-0 20-0mA	1 Switch to Automatic Mode	E Type E (TC)
dCo Double-Sided (+/-) PID Control		PuTr Process Value Transmitter	4-20 4-20mA	2 Switch to Automatic Mode and make "Int=0"	J Type J (TC)
PFb Feedback Valve Control		SPTr Set Point Transmitter	20-4 20-4mA	3 Switch to Manuel Mode	K Type K (TC)
bnd Open-Loop Valve Control				4 Switch to Manuel Mode and make "Out = 0"	L Type L (TC)
					N Type N (TC)
					R Type R (TC)
					S Type S (TC)
					T Type T (TC)
					U Type U (TC)
					Pt Pt-100 (RT)
					0R20 0-20mA (Linear)
					4R20 4-20mA (Linear)
					0-50 0-50mV (Linear)
					0.0-1.0V (Linear)
					0.2-1.0V (Linear)

12. TABLES

Table 15	Table 16
0 Only Process Value can be accessed	0 None of the Parameters can be edited
1 Process and Set Values can be accessed	1 Only Set Value can be edited
2 Operation Screen Parameters can be accessed	2 Operation Screen Parameters can be edited
3 Reserve	3 Reserve
4 Reserve	4 Reserve
5 CLbr Page Parameters can be accessed	5 CLbr Page Parameters can be edited
6 SPTr Page Parameters can be accessed	6 SPTr Page Parameters can be edited
7 RLnF Page Parameters can be accessed	7 RLnF Page Parameters can be edited
8 oLnF Page Parameters can be accessed	8 oLnF Page Parameters can be edited
9 CLbr Page Parameters can be accessed	9 CLbr Page Parameters can be edited

Levels with large numerals in Tables-15 and Tables-16 contains previous levels

13. INPUT TYPES - RANGES

TEMPERATURE SENSORS

Sensor Type	Standart	Temperature Range		
		(°C)	(°F)	
Type B	b	IEC60584-1	100 , 1820	140 , 3308
Type E	E	IEC60584-1	-200 , 840	-328 , 1544
Type J	J	IEC60584-1	-200 , 1120	-328 , 1562
Type K	K	IEC60584-1	-200 , 1360	-328 , 2480
Type L	L	DIN43710	-200 , 900	-328 , 1652
Type N	n	IEC60584-1	-200 , 1300	-328 , 2372
Type R	r	IEC60584-1	-40 , 1760	104 , 3200
Type S	S	IEC60584-1	-40 , 1760	104 , 3200
Type T	t	IEC60584-1	-200 , 400	-328 , 752
Type U	U	DIN43710	-200 , 600	-328 , 1112
Pt-100	Pt	IEC60751	-200 , 840	-328 , 1544

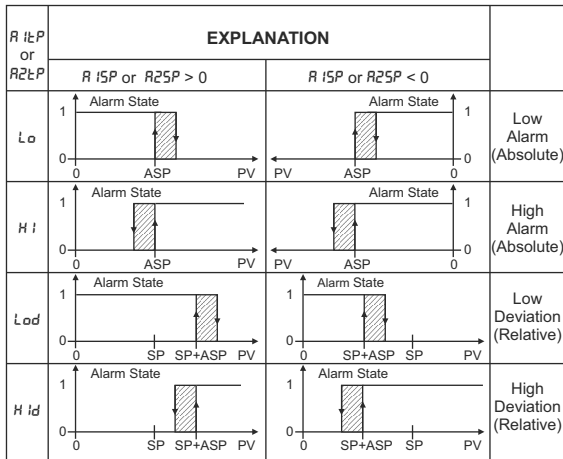
14. LINEAR INPUTS

Type	Range
Current 0A20	0-20 mA DC
Current 4A20	4-20 mA DC
Voltage 0u50	0-50 mV DC
Voltage 00u1	0-1 V DC
Voltage 02u1	0.2-1 V DC

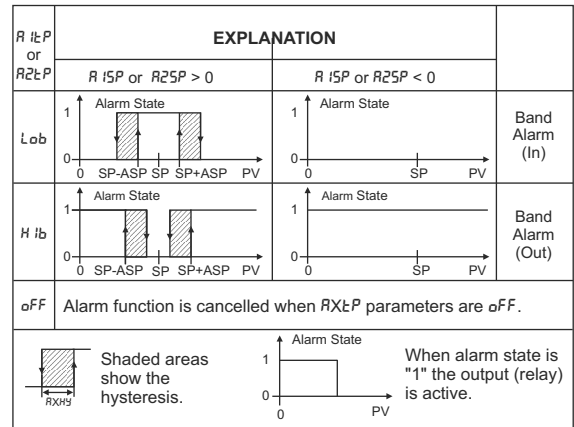
15. ERROR MESSAGES

Message	Meaning	Remedy
aPE _n	The connection of the sensor is broken.	Check the sensor and the sensor connections.
UFL	The process value is below the sensor type-temperature interval.	Check the sensor and the input type specified by the <i>inPt</i> parameter.
aFL	The process value is above the sensor type- temperature interval.	
nnnn	The process value is above the value that can be displayed.	Check the analog value on the input terminal and the scalar specified by the <i>dP</i> , <i>zEr_o</i> and <i>5PR_n</i> parameters.
uuuu	The process value is below the value that can be displayed.	

16. ALARM TYPES



16. ALARM TYPES



17. AUTO-TUNE

- Auto-tuning matches the characteristics of the controller to the process being controlled in order to obtain good control. Tuning involves calculating and setting the values of the PID parameters. The Auto-tuner works by switching the output on and off to induce an oscillation in the process value. From the amplitude and period of oscillations PID parameters are calculated.
- Auto-tune can be performed at any time, but normally it is performed only once during the initial commissioning of the process. However, if the process under control subsequently becomes unstable (because its characteristics have changed), you can re-tune again for the new conditions.
- In order to start Auto-tune process:
 - 1- Set the *EtYP* parameter in *aLnF* page as *5Lo*.
 - 2- Set the output that control the process to *Lo-1*.
 - 3- Set the control set point to the value at which you will normally operate the process. Consider also the process value may exceed the control set point while in Auto-tuning.
 - 4- Set the *HYS* parameter in *EtUnE* page as *0.1* (if *dP=1*) or *1* (if *dP=0*).
 - 5- Set the *Rt* parameter in *EtUnE* page as *on* to commence Auto-tuning process. Press button to revert the normal operation.
- The lower display and MN led will flash to indicate that tuning is in progress.

17. AUTO-TUNE

- After a few cycles of oscillation the tuning is completed and the calculated PID parameters *Pb-1*, *It* and *dE* are stored.
- While the Auto-tuning in progress if *Rt* parameter is set the *oFF* or operating power of the controller is interrupted Auto-tune progress is stopped and old PID values are retained.

18. MANUAL TUNING

If for any reason Auto-tuning gives unsatisfactory results, the controller can be tuned manually. There are a number of standard methods for manual tuning. The one described here is the Ziegler-Nichols method. With the process at its normal running temperature:

- 1- Set the *EtYP* parameter in *aLnF* page as *5Lo*.
- 2- Set the output that control the process to *Lo-1*.
- 3- If the control output is relay, set the *CPrd* parameter in *aLnF* page as *2*.
- 4- Set the *It*, *dE* and *HYS* parameters in *EtUnE* page as *0*.
- 5- Ignore the fact that the temperature may not settle precisely at the set point.

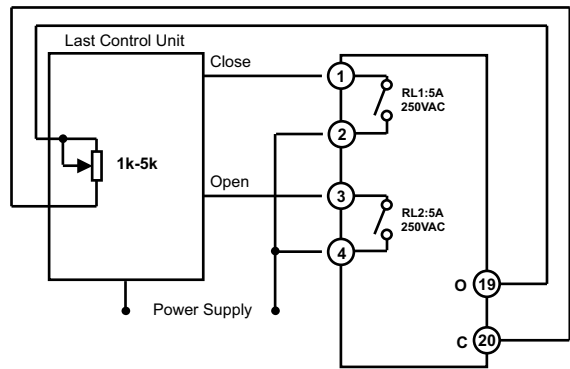
18. MANUAL TUNING

6- If the temperature is stable, reduce the proportional band $Pb-1$ so that the temperature just starts to oscillate. If the temperature is already oscillating, increase the proportional band until it just stops oscillating. Allow enough time between each adjustment for the loop to stabilize. Make a note of the proportional band value (B) and the period of oscillation (T).

7- Set the $Pb-1$, $I\dot{t}$ and $d\dot{t}$ parameters values according to the calculations given below.

Control Type	Proportional Band ($Pb-1$)	Integral Time ($I\dot{t}$)	Derivative Time ($d\dot{t}$)
P	2xB	0	0
PI	2.2xB	0.8xT	0
PID	1.7xB	0.5xT	0.12xT

19. FEEDBACK VALVE CONTROL



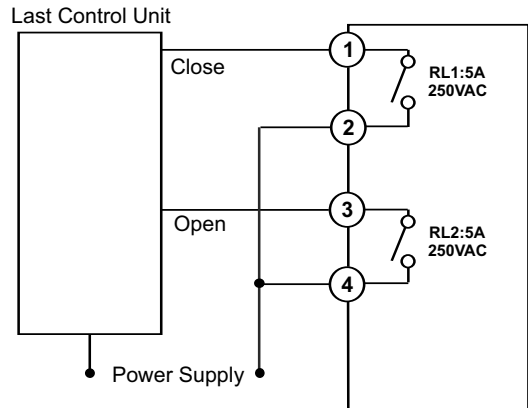
19. FEEDBACK VALVE CONTROL

As shown in figure, control of the feedback controlled valve can be made with a servomotor connected to the relays and the 19-20th terminals on E-49 & E-94, and a potentiometer (1k-5k).

The parameters of this control, are the $\dot{C}\dot{t}\dot{Y}P$, $dbnd$, $SrUL$ and $SrUH$ parameters, in the output configurations page $\alpha\dot{C}nF$. These parameters are as follows;

- The $\dot{C}\dot{t}\dot{Y}P$ parameter should be set to PfB , for this control.
- The $dbnd$ parameter is used to prevent relays from opening and closing frequently, during the control. Its unit is given as a percentage of the location data. Its value determines the death band value for both to stay open.
- The $SrUL$ parameter, keeps the location data of the controlled valve in the fully closed state. With this parameter on the display, \downarrow key starts the action in motor-active direction. In the fully closed state, the value shown on the display can be saved by pressing $\boxtimes\downarrow$ keys.
- The $SrUH$ parameter, keeps the location data of the controlled valve in the fully open state. With this parameter on the display, \uparrow key starts the action in the motor-active direction. In the fully active state, the value shown on the display can be saved by pressing $\boxtimes\uparrow$ keys.

20. OPEN - LOOP VALVE CONTROL



20. OPEN - LOOP VALVE CONTROL

Using the relays on E-49 & E-94, an open-loop valve control can be made, as shown in figure. Parameters related with this control, are the $\dot{C}\dot{t}\dot{Y}P$, $dbnd$ ve $\dot{t}r\dot{t}\dot{n}$ parameters in the $\alpha\dot{C}nF$ page. The explanation for the parameters are;

- For this control to be made, the $\dot{C}\dot{t}\dot{Y}P$ parameters should be set to bnd .
- The $dbnd$ parameter is used to prevent the relays from opening and closing frequently, during the control. Its unit is given as percentage of the location data. Its value determines the death band value for both relays to stay open.
- The $\dot{t}r\dot{t}\dot{n}$ parameter is the time, in which the valve switches to full-closed from full-open state, when energized. Its unit is seconds.



TS EN ISO 9001
Quality Management System Certificate

KY-49-1216-0
KY-94-1216-0